

Table 3-9. Explanation of Launch Trajectory Acquisition System
2400-b/sec Format*

| Bit No. | Description |
|---|--|
| 1-13 | Satellite ID Code (binary) |
| 14-17 | Vehicle ID Code (binary) |
| 18-26 | Day of year (binary) |
| 27-30 | Format type (binary) = 0000 for LTAS |
| 31-34 | Time of Day - Tenths of seconds (binary - LSB = 0.1 sec) |
| 35-51 | Time of Day - Seconds (binary - LSB = 1.0 sec) |
| 52-60 | Site ID (refer to appendix C, table C-2) |
| 61-87 | E-position component (meters) |
| 88 | Sign for E (0 = positive) (1 = negative. When negative, bits 61-87 will be 2's complement.) |
| 89-90 | PSC (Position Scale Code) (Value by which all position components should be multiplied if the field length is exceeded.) 00 - x 1 01 - x 10 10 - x 10 ³ 11 - x 10 ¹⁰ |
| 91-117 | F-position component (meters) |
| 118 | Sign for F (0 = positive) (1 = negative. When negative, bits 91-117 will be 2's complement.) |
| 119-120 | VSC (Velocity Scale Code) (Value by which all velocity components should be multiplied if the field length is exceeded.) 00 - x 1 01 - x 10 (All other scales are invalid) |
| 121-147 | G-position component (meters) |
| *30 bits = 1 word; bit No. 1 = first bit transmitted. | |

TABLE 3-5. Explanation of Common Flagging Sequence
2400-b/sec Format* (cont)

| Bit No. | Description |
|---|--|
| 148 | Sign for G (0 = positive) (1 = negative. When negative, bits 121-147 will be 2's complement.) |
| 149 | Optical Track Bit (OTB) (always = 0) |
| 150 | PTF (Plus Time Flag) (1 = using plus time) |
| 151-164 | F-velocity component (meters/second) |
| 165 | Sign for F 0 = positive (1 = negative. When negative, bits 151-164 will be 2's complement.) |
| 166-179 | E-velocity component (meters/second) |
| 180 | Sign for E 0 = positive (1 = negative. When negative, bits 166-179 will be 2's complement.) |
| 181 | L liftoff 1 = liftoff has occurred |
| 182 | P plunge mode 1 = plunge |
| 183-184 | P/W (Pulse Width) 00 - 1.0 μ sec 01 - 2.4 μ sec 10 - 5.0 μ sec 11 - 10.0 μ sec |
| 185 | RI (Refraction correction) (0 = out)(1 = in) |
| 186 | DI (Droop) (0 = out) (1 = in) |
| 187 | PO (Paramp) (0 = off) (1 = on) |
| 188 | RO (Radiation) (0 = off) (1 = on) |
| 189 | LO (0 = Single LO) (1 = Dual LO) |
| 190 | B/S (Beacon/Skin) (0 = skin) (1 = beacon) |
| 191 | T (Track bit) (0 = off) (1 = on) |
| 192 | Q (Quality bit) (0 = bad) (1 = good) |
| *30 bits = 1 word; bit No. 1 = first bit transmitted. | |

Table 3-9. Explanation of Launch Trajectory Acquisition System
2400-b/sec Format* (cont)

| Bit No. | Description | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------|--|---|--------------------------|---|----------|---|---|---|-------------|---|---|---|------------------|---|---|---|-------------------|---|---|---|--------------------------|---|---|---|-----------------|---|---|---|-------------------|
| 193-195 | <p>Mode (Bit No. 193 194 195)</p> <table> <tr> <td>0</td> <td>0</td> <td>0</td> <td>= manual</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>= autotrack</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>= computer drive</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>= on-axis orbital</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>= on-axis powered flight</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>= on-axis coast</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>= autotrack coast</td> </tr> </table> | 0 | 0 | 0 | = manual | 1 | 0 | 0 | = autotrack | 0 | 1 | 0 | = computer drive | 1 | 1 | 0 | = on-axis orbital | 0 | 0 | 1 | = on-axis powered flight | 1 | 0 | 1 | = on-axis coast | 0 | 1 | 1 | = autotrack coast |
| 0 | 0 | 0 | = manual | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 0 | = autotrack | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 0 | = computer drive | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 1 | 0 | = on-axis orbital | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 1 | = on-axis powered flight | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 1 | = on-axis coast | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 1 | = autotrack coast | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 196-209 | G-velocity component (meters/second) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 210 | Sign for G (0 = positive) (1 = negative. When negative bits 196-209 will be 2's complement.) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 211-217 | Checksum (see note) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 218-224 | Spares | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 225-240 | <p>Sync bits. Bits 225-240 will have the following patterns:</p> <p>0-0-0-1-1-0-1-0-0-0-0-1-1-0-1-0 on one message and 0-0-0-1-1-0-1-0-0-0-0-0-0-1-0-1 on the next.</p> <p>Note</p> <p>LTAS 2400-b/sec checksum algorithm:</p> <ol style="list-style-type: none"> 1. The first 210 data bits are treated as fourteen words of 15 bits each. These words are summed, treating them as positive integers, in an accumulator capable of handling a 19-bit positive integer sum. 2. This sum is split up into three parts: the most significant 7 bits, the next most significant 6 bits, and the least significant 6 bits, and these three words are summed, treating them as positive integers, in an accumulator capable of handling an 8-bit positive integer sum. 3. The least significant 7 bits of these sums become the checksum. | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

* 30 bits = 1 word; bit No. 1 = first bit transmitted.